

# **Device for finishing car body components through robots has further guide for returning robot to starting position to allow continuous movement of component**

**Publication number:** DE10102758 (A1)

**Publication date:** 2002-07-25

**Inventor(s):** OBERHOLTHAUS RIGBERT [DE] +

**Applicant(s):** VOLKSWAGEN AG [DE] +

**Classification:**

**- international:** B23P21/00; B25J5/00; B25J9/00; B62D65/02; B23P21/00;  
B25J5/00; B25J9/00; B62D65/00; (IPC1-7): B23P21/00;  
B25J13/00; B25J5/00; B62D65/02

**- European:** B23P21/00B; B25J5/00; B25J9/00P; B62D65/02

**Application number:** DE20011002758 20010123

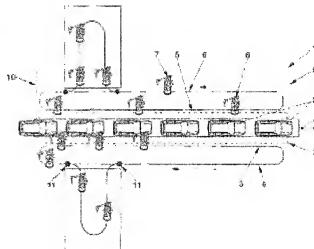
**Priority number(s):** DE20011002758 20010123

## **Cited documents:**

- DE3917544 (A1)
- DE3720175 (A1)
- DE3516284 (A1)
- DE29712348U (U1)
- DE69012532T (T2)

## **Abstract of DE 10102758 (A1)**

The device has a robot mounted movable on a guide (5) between two end positions whereby the device for returning the robot (7,8) into the starting position has a further guide (6). The guides are arranged to run round between the end positions and can include a branch (11) for selectively bringing the robot in or out of use.



Data supplied from the **espacenet** database — Worldwide